

Roll No.

24357

B. Tech. 6th Semester (M.E.)

Examination – May, 2014

Automatic Control

Paper : ME-308-F

Time : Three hours]

[Maximum Marks : 100

Before answering the questions, candidates should ensure that they have been supplied the correct and complete question paper. No complaint in this regard, will be entertained after examination.

Note : Question number 1 is *compulsory* and attempt *five* questions in total, selecting *one* question from each Unit.

1. (a) Define Transfer function . $10 \times 2 = 20$
- (b) What do you mean by forward path and feedback path in use of signal flow graph ?
- (c) Define steady state response.
- (d) What do you mean by closed loop transfer function?

- (e) Define the term gain margin.
- (f) What do you mean by process delays ?
- (g) What is the application of control valve ?
- (h) State final value theorem.
- (i) Define settling time.
- (j) Write the generalized state equation in matrix form .

SECTION – A

- 2. Classify and explain different types Engine governing in detail. 20
- 3. Discuss the Principal working of Hydraulic and pneumatic controllers. 20

SECTION – B

- 4. Write short notes on : 20
 - (a) Error constant
 - (b) Proportion cum derivative control
 - (c) Polar plots
- 5. For a unity feedback system, with open loop transfer function of $\frac{K}{s(0.2s^2 + 0.5s + 1)}$, draw for $K=1$, the open loop frequency response plot and find the value of peak 'M' and the frequency at which it occurs. 20

SECTION - C

6. Draw complete Nyquist plot for a control system with open loop transfer function of $\frac{1}{[s^4(s+5)]}$ and find if the system is stable or not. 20
7. Sketch root loci for a system with open loop transfer function of $\frac{K(s+2)}{(s+3)(s^2+4s+5)}$. Also find the value of K, at which stability occurs. 20

SECTION - D

8. Write short notes on : 20
- (i) Root locus method
 - (ii) Nyquists Criterion
9. Obtain a state space representation of $\frac{y(s)}{u(s)} = \frac{12(1-s)}{(s+2)(s+5)}$, Also find expression for output y(t) for a unit step input u(t). Take initial conditions as zero. 20